

**LIST OF PATENTS AND PUBLICATIONS FOR APPLICANTS'
INFORMATION DISCLOSURE STATEMENT**

INFORMATION DISCLOSURE STATEMENT BY APPLICANT	Application Number	10/718,913
	Filing Date	November 21, 2003
	Inventor	McBean et al
	Art Unit	3772
	Examiner	Brown, Michael
	Atty Docket	1118/A04

U.S. Patent Documents					
Examiner's Initials	Ref. No.	Document No.	Issue Date	Inventor	Class
	BA	3,769,636	11-1973	Friedman	623/24
	BB	5,112,296	05-1992	Beard et al.	602/28
	BC	5,835,005	11-1998	Furukawa et al.	370/400
	BD	5,888,212	03-1999	Petrofsky et al.	623/24
	BE	6,616,579	09-2003	Reinbold et al.	482/91

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U.S. Patent Publication Documents					
Examiner's Initials	Ref. No.	Document No.	Publication Date	Inventor	Class
	BF	2002/0169402	11-2002	Hatton et al.	602/26
	BG	2003/0212356	11/13/2003	Scorvo	602/20

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Non-Patent References		
Examiner's Initials	Ref. No.	Document Number, Publication Date, Inventor
	BH	Abul-Haj, et al., "Functional Assessment of Control Systems for Cybernetic Elbow Prostheses – Part II: Application of the Technique", 1990, IEEE Transactions on Biomedical Engineering, Vol. 37, No. 11, pages 1037-1047
	BI	Bowen, et al., "Surface EMG and Motor Control of the Upper Extremity in Muscular Dystrophy: A Pilot Study", 2002, IEEE Bioengineering Conf., pages 289-290
	BJ	Downes, et al., "Distributed Control of an Electronically Powered Hip Orthosis", 1994, IEE Control Conference, pages 24-30
	BK	Fukuda, et al., "EMG-Based Human-Robot Interface for Rehabilitation Aid", Proceedings of the 1998 IEEE International Conference on Robotics and Automation, pages 3492-3497
	BL	Harwin, et al., "Criteria for Interfacing and Control of a Powered Upper Extremity Orthosis", RERC on Rehabilitation Robotics Applied Science and Engineering Laboratories, University of Delaware/A.I. DuPont Institute, Rehabilitation R&D Progress reports, 1995, Vol. 33, pg. 215
	BM	Kawamura, et al., "A Design of Motion-Support Robots for Human Arms using Hexahedron Rubber Actuators", 1997, IROS, IEEE, pages 1520-1526
	BN	Kazerooni, "Stability and Performance of Robotic Systems Worn by Humans", University of Minnesota, Mechanical Engineering Dept., May 13-18, 1990 IEEE, Vol. 1, pages 558-563,
	BO	Kiguchi, et al., "An Exoskeleton System for Elbow Joint Motion Rehabilitation", Proceedings of the 2003 IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM 2003), pages 1228-1233
	BP	Lee, et al., "A New Exoskeleton-type Masterarm with Force Reflection: Controller and Integration", 1999, IEEE/RSJ International Conference on Intelligent Robots and Systems, pages 1438-1443

Examiner Signature: _____

Date Considered: _____

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609; draw a line through the citation *if not* in conformance and not considered. Include copy of this form with next communication to applicant.

Identification of Person Making This Information Disclosure Statement

The person making this statement is the practitioner who signs below on the basis of the information supplied by the inventor and in the practitioner's file.

Respectfully submitted,

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